WiSenMeshNET: Omni Tilt & Distance Node Wireless Monitoring System



This internally powered dual sensor node allows measurement of tilt in any axis from a horizontal plane and a distance to any surface upto 300m away without a reflector. With a full tilt range (360° any axis) and very high accuracy ($\pm 0.002^\circ$) and resolution ($\pm 0.0001^\circ$), in addition to distance measurement ($0.05m \sim 300m$) with a high accuracy ($\pm 1mm$) and resolution ($\pm 0.1mm$). The omni-axis sensors can be installed in any orientation and automatically detect the horizontal plane.

The nodes also include an integrated temperature sensor and wireless mesh radio transmitter via the external antenna.

The battery lifespan is up to 5 years at hourly readings.

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WiSenMeshNET nodes communicate via bespoke encrypted mesh radio technology can be up to 400m from each other or the SmartGateway. The sensors mesh together and automatically form a network relaying data off each other (up to 10 sub mesh levels of data hop) and back to a central data hub called a SmartGateway which contains the data logging functions, radio mesh control systems and external communication to the WiSen cloud-based datacentre or local hosted system.

It is also available in a configuration designed specifically for rail track monitoring with an integrated internal antenna.

FEATURES

- WiSenMeshNET Node
 Omni-axis tilt 360° range
 ±0.002° accuracy
 ±0.0002° precision
 ±0.0001° resolution
 Distance measurement 0.05m ~ 300m
- Distance resolution ±0.1mm
- Intelligent node/repeater
- Battery life up to 5 years
- 1 second to 1 hour variable readings

WISEN INNOVATION

- End user configurableRugged Housing
 - IP66
 - Gravity Orientation Sensor

WiSenMeshNET: Omni Tilt & Distance Node

| PHYSICAL PROPERTIES | | | | |
|--------------------------------------|--|---------------------------------|-----------------------------------|----------------------------------|
| Dimensions (L x W x H) | 100mm x 100mm x 60mm (excluding antenna) | | | |
| Weight | 0.65kg | | | |
| Casing and PaintingMaterials | Aluminium-Alloy & Epoxy Polye | ster Powder Coating | | |
| International Protection Mark Rating | ≥IP66 | | | |
| Operating Temperature | -10 to +50°C | | | |
| LOCAL STORAGE | | | | |
| Local Flash Memory Storage | Min. 450 Data Packets | | | |
| POWER | | | | |
| Primary DC Power | 1 xER34615 Lithium D Cell Batte | ery | | |
| Battery Life Expectancy 1, 2 | | | | |
| | Sampling Time Interval - T | Duration (Days) ^{1, 2} | Duration (Months) ^{1, 2} | Duration (Years) ^{1, 2} |
| | 1 Min | 46 | 1.5 | 0.1 |
| | E Mino | 170 | 5.0 | 0.5 |

| Т | Duration (Days) | Duration (Months) | Duration (rears) |
|---------|-----------------|-------------------|------------------|
| 1 Min | 46 | 1.5 | 0.1 |
| 5 Mins | 179 | 5.8 | 0.5 |
| 15 Mins | 538 | 17.7 | 1.5 |
| 30 Mins | 981 | 32.2 | 2.7 |
| 1 Hour | 1937 | 63.7 | 5.3 |

Quoted battery life are best case scenarios with minimal hops. For example, a node taking 9-10 hops could lead to a reduction of 40%. Please contact WiSen for further advice.
 Laser Distance measurement duration greater >3.0 secs caused by non-reflective target surface or light pollution will affect battery performance.

| Accuracy Stop Voltage | 2.7VDC |
|---|---|
| Mesh Stop Voltage | 2.1VDC |
| Battery Connection | Standard Aluminum Battery Holder |
| Working Current (DC) | Max. 500mA (Typically 220mA) |
| PRIMARY SENSOR – DISTANCE LASER | |
| Sensor Type | Optical Laser Distance Sensor |
| Laser Class | Class II (655nm – Visible Red) |
| Range | 0.05m-33m (1F07) 0.05m-100m (1F08) 0.05m-300m (1F09) |
| Accuracy | ± 1mm |
| Precision | ± 0.15mm (1 Sigma) |
| Resolution | ± 0.1mm |
| Laser Lens Durability | >= 500Hrs@3Hz@50°C or 2500Hrs@3Hz@25°C |
| Laser Reading Time | Upto 2-3 seconds depending on conditions |
| Quantity of Samples per Reading | Typically, 5 |
| SECONDARY SENSOR - TILT | |
| Sensor Type | MEMS Triple-Axis Tilt Sensor |
| Range | ±90° per axis |
| Accuracy | For ± 0.0° to ± 2.0° ± 0.0020° 7.20" 0.0349mm/m (or mrad) |
| | For $\pm 2.0^{\circ}$ to $\pm 90^{\circ}$ |
| Precision | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) ± 0.0001° 0.36" 0.0017mm/m (or mrad) |
| Precision Resolution Long Term Stability | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) ± 0.0001° 0.36" 0.0017mm/m (or mrad) @ 10 Years 0.014° |
| Precision Resolution Long Term Stability Vibration Resistance | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in RADIO SPECIFICATIONS | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in RADIO SPECIFICATIONS Protocol | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in RADIO SPECIFICATIONS Protocol Radio Frequency | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in RADIO SPECIFICATIONS Protocol Radio Frequency SERVICE INSPECTION | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± 0.00020° 07.20" 0.00349mm/m (or mrad) ± 0.0001° 0.36" 0.0017mm/m (or mrad) @ 10 Years 0.014° Conformance to EN60068-2-64:2004 & EN50125-3:2003+COR R2010 Standards for railtrack vibration/shock acceleration for on sleeper placement associated to peak vibration 800m/s² / 2ms or 81.6g 1000g (Powered Mode) mpact greater than quoted number. Care and Consideration must be undertaken for this precise equipment. WiSenMeshNET® proprietary radio encryption 2.4GHz System |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in RADIO SPECIFICATIONS Protocol Radio Frequency SERVICE INSPECTION Inspection Period | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |
| Precision Resolution Long Term Stability Vibration Resistance Impact Resistance (2) (2) The tilt sensor should not be subject to an in RADIO SPECIFICATIONS Protocol Radio Frequency SERVICE INSPECTION Inspection Period CERTIFICATION | For ± 2.0° to ± 90° ± 0.0050° 18.0" 0.0872mm/m (or mrad) ± <0.00020° 07.20" 0.00349mm/m (or mrad) |



| Network Rail | PADS Number: - |
|--------------------|----------------|
| London Underground | Reg Number: - |

ACCESSORIES

| Radio Antennas | |
|----------------|---|
| WA029-00002 | WiSenMeshNET Whip Mesh Antenna |
| | (+5dBi/195mm) |
| WA029-00039 | WiSenMeshNET Whip Mesh Antenna |
| | (+10dBi/395mm) |
| | |
| Power Supply | |
| WB016-00016 | 3.6V ER34615 19AHr D Cell Lithium Battery |

| Mounting | |
|---|--|
| WM028-00155 | WiSen L-Bracket for Tilt Sensor Node* |
| WM028-00187 | WiSen Flat Mounting Plates with U Clamps for |
| | Sensor Nodes* |
| WM028-00203 | WiSen Railway Two-Part Aluminium Mounting |
| | Plate |
| *Compatible with magnet fixings for non-intrusive installations | |
| | |

INSTALLATION ORIENTATIONS AND ASSOCIATED X, Y & Z AXIS TILT RESULTANT VALUES

The below is from 'Load Sensing' Datasheets. I think it would be good to create similar. We would need to draw our node then orientate so we have same sign outcome as below









